

ANABAS

Taking Collaboration to the Next Level

“We have seen the future

and it is here...”

Presented by
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Phoenix, A Collaborative Sensor-Rich Application Development/Deployment Framework

by

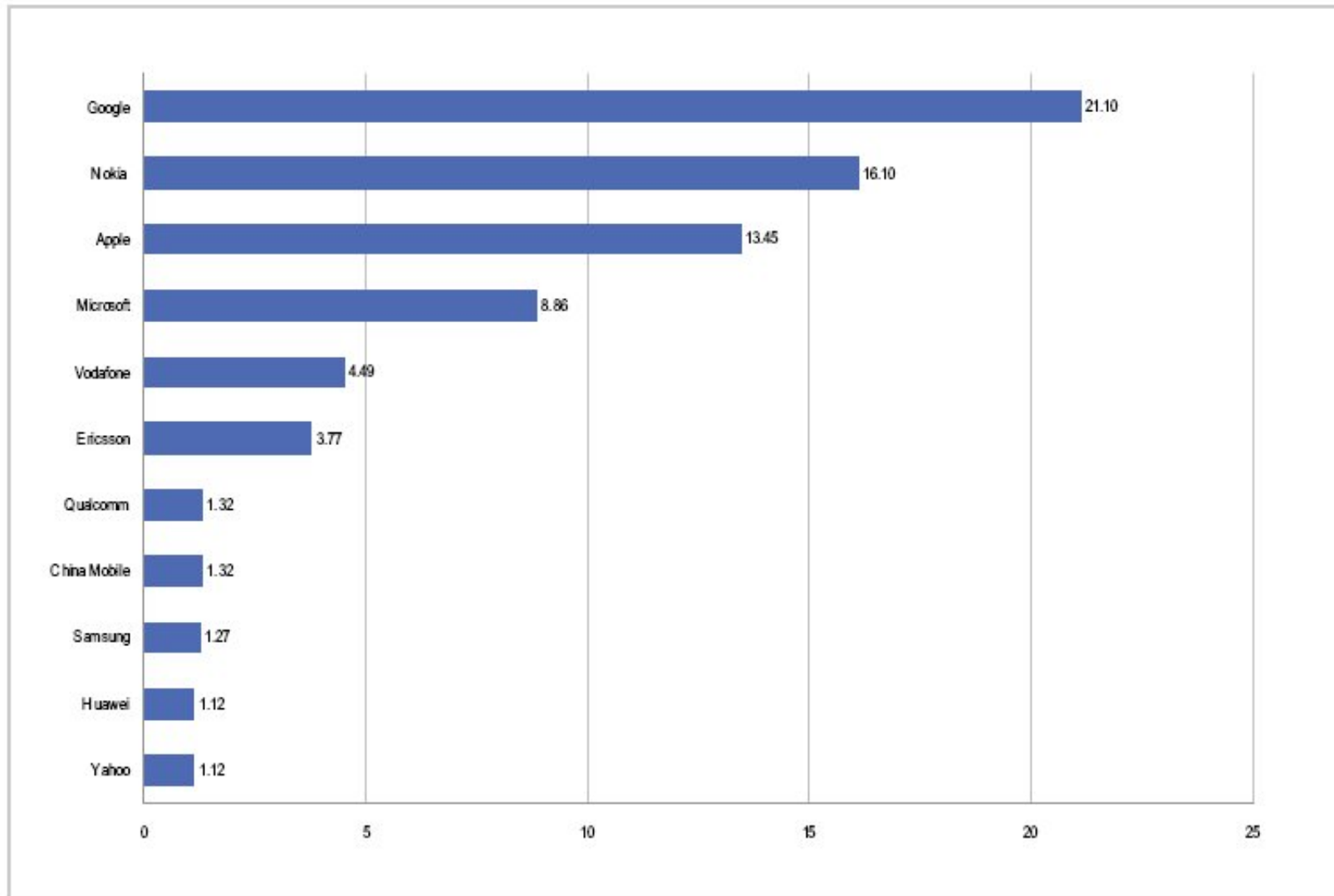
Alex Ho, Anabas
Geoffrey Fox, Anabas/Indiana University

Motivation

- The number of mobiles exceeds the number of PCs
 - Samsung projects mobile market size of 1.2 billion units in 2008
 - Gartner reported about 271 million units of PC sold in 2007
- Information is playing an increasingly important role in mobile applications
- Increased use of low cost sensors in commercial and consumer environments
- Information age versus Integration age
 - Too much information. Need integration and relevancy.
- Increase interests in real-time collaboration for social networks

Global Mobile Survey Sponsored by Qualcomm & Telco 2.0

- Which companies have the most impact in shaping the future of mobile communications?



Quest for Dominance in Mobile Application Development Platforms

- Nokia Symbian – open
- Google Android - open
- Apple iPhone – restricted open

Open systems ensure

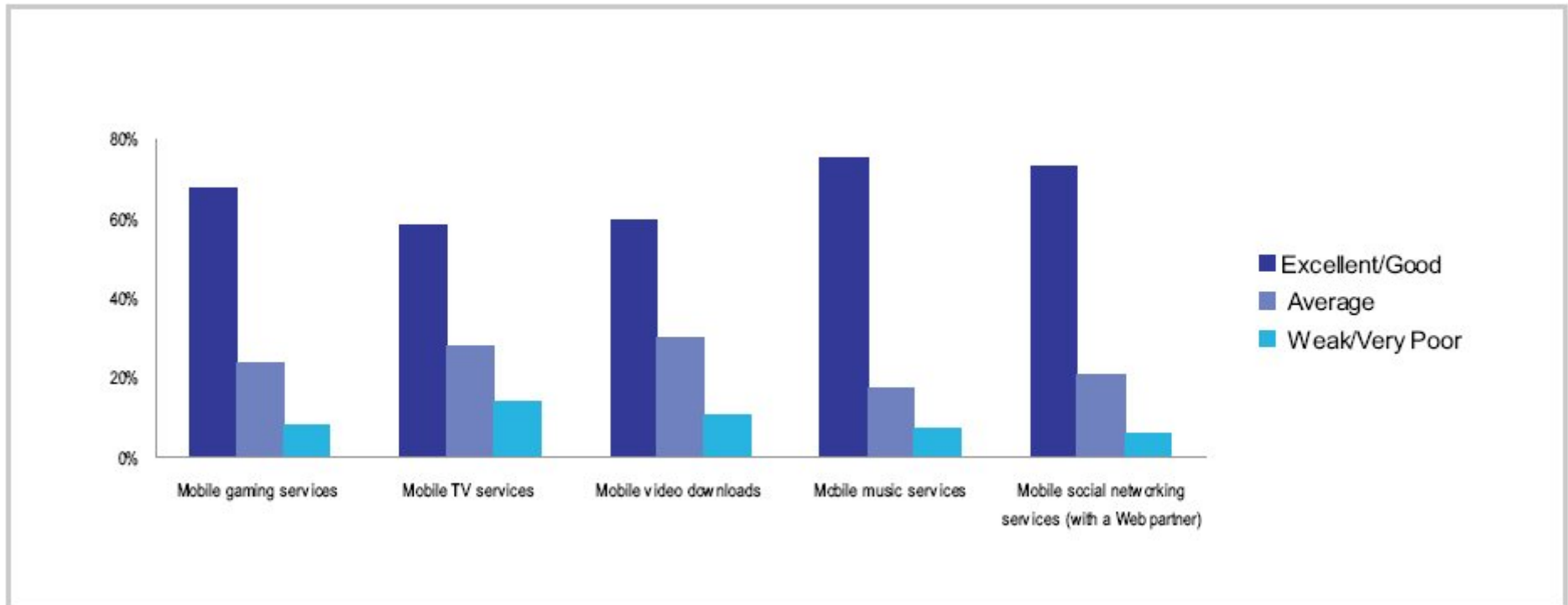
- application openness is maintained on the mobile Internet
- takes about 20% off a mobile's cost (software)
- facilitates growth of third party applications to drive adoption

- This talk does not focus on what is and may be a killer app.
- We focus on providing a framework that facilitates a world of talented developers to build and deploy creative and potentially killer-applications easily on
 - low power, battery-based devices such as a mobile handset, and
 - an open platform that is designed for smart mobile devices such as Symbian

Understanding Application Framework Requirements from an Application Perspective

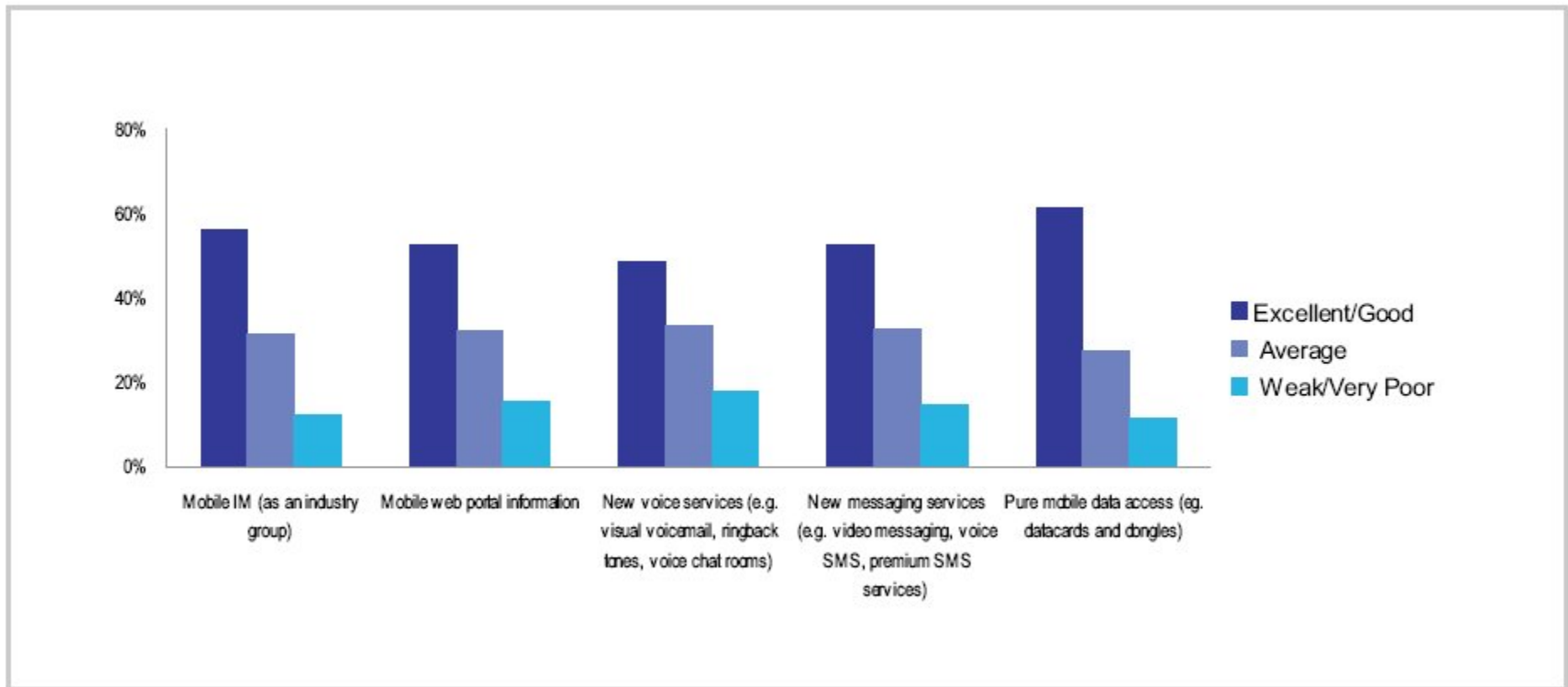
Global Mobile Survey Sponsored by Qualcomm & Telco 2.0

- What are the opportunities for growth in the mobile service and application areas?



Global Mobile Survey Sponsored by Qualcomm & Telco 2.0

- What are the opportunities for growth in the mobile service and application areas?



Some Sample Sensor-Centric Android Applications

- Accelerometer and Compass
 - Open Google Map's StreetView functionality streaming over a 3G network
 - Using the built-in 3D accelerometer and compass, a user can take a "look" around a street and location simply by holding the handset and moving it around.
- Camera, GPS, Motion Sensor and web services
 - Lay and display location services over live imagery.
 - By pointing a camera at a building a user will be presented with the building's name/location, and distance from the user.
- Camera and GPS
 - Social network around geographical content
 - Search for places to go, exciting routes
 - Create navigation by picture and share

Samples Collaborative Android Applications

- Collaborative Painting
 - Share a canvas and invite friends to draw
 - Draw on photographs
- Instant Messaging App
 - Location-aware mobility communication among friends
 - Interactive and synchronous map sharing
- Jigsaw: Image-processed Whiteboard Sharing
 - Utilizing image processing techniques like edge detection, geometric transformation and image enhancement to capture whiteboard data
 - Share the whiteboard and its data

Observations on mobile applications

- Interested in collaboration and sharing
- Sensor-Rich
- Access outside services like maps, music, TV, GIS

What do the observations really mean for mobile apps?

- Social network is important. A framework that has built-in support for comprehensive, effective and efficient collaboration will enable more addictive social networks.
- Environmental sensor information from mobiles are of interest. Mobiles are naturally globally distributed. The capability to harness and manage distributed sensor streams and at the same time supporting real-time sharing in an application development and deployment framework will substantially simplify and make it much easier for developers to focus on building the next Myspace-like killer-app by leaving the complex distributed deployment and information management task to the framework.
- Take full advantage of the mobile network. Not everything need to be done on mobiles for mobile apps. Some tasks are preferred and better done outside mobiles. Supporting easy access to outside services like maps, music etc is an important aspect of the mobile Internet. It will even be more compelling if mobile apps running on an Nokia-led mobile Internet could be enriched with transparent access to and interaction with any outside services, including the zillions of existing software capabilities that normally run on multi-cores or servers, in addition to supporting retrieval of multimedia data like other competitors.

Test Case 1: How about an interesting yet challenging cross-device mobile application? Can it be done easily?

- Do all the great things with mobile camera, GPS, maps, GIS, compass
- Capture the lovely view with other environmental data of the surroundings
- Add annotations and overlays
- Share it synchronously with not only social networks on mobiles but also devices like a digital picture frame in grand-parents house

Test Case 2: For the sake of stimulating thoughts and deriving architectural requirements, how would one develop an Android Jigsaw-like whiteboard application **easily** on Symbian?

Question: What is a viable, consistent architecture to support easy development and deployment of these test case applications and all others we looked at earlier?

A Side Track WHY COLLABORATION

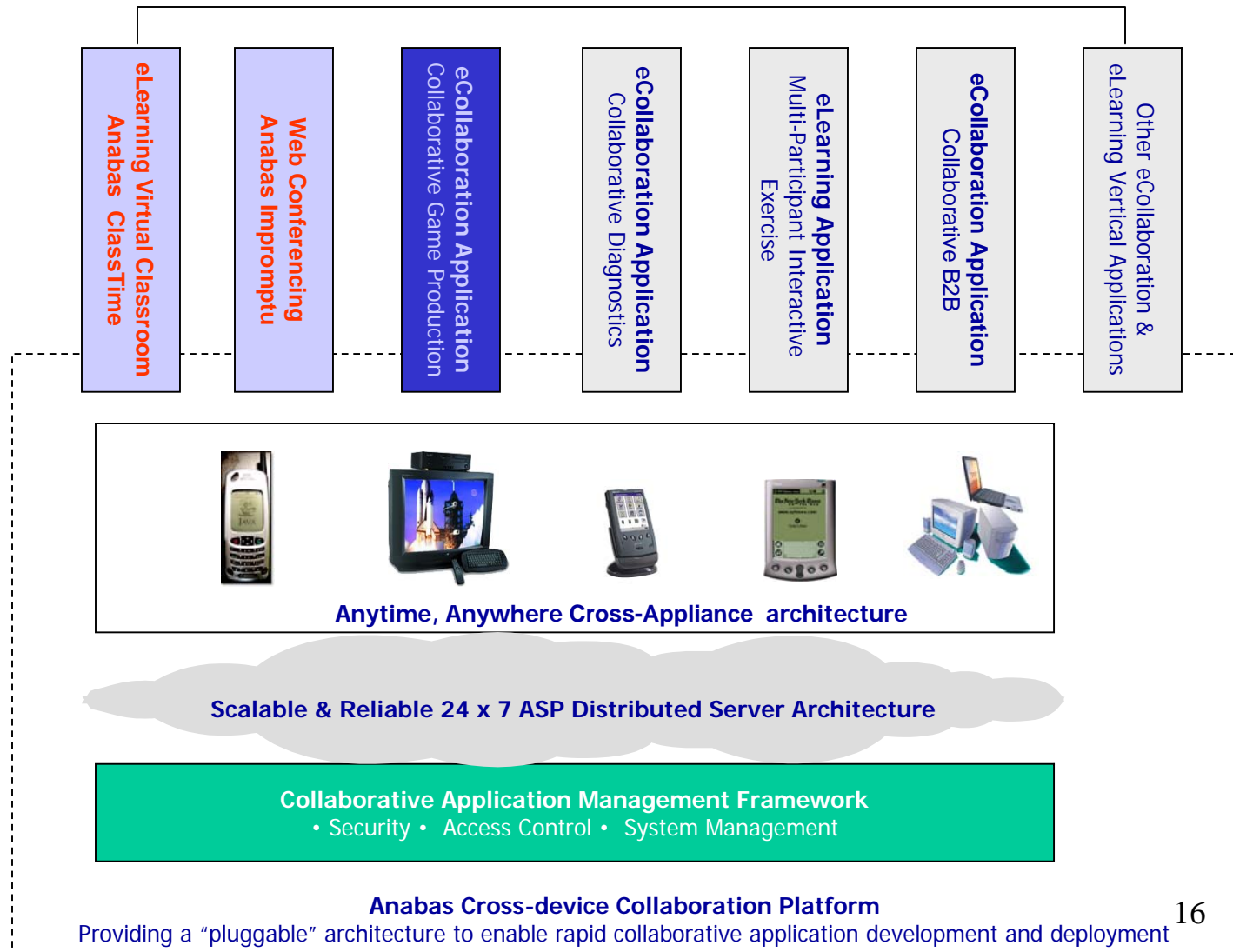
“Many of us envisioned an online world where constellations of PCs, servers, smart devices, and Internet-based services can collaborate seamlessly. Business will be able to share data, integrate their processes, and join forces to offer customized, comprehensive solutions to their customers. And the information you or your business need will be available wherever you are - whatever your computing devices you are using.

That vision has not yet been achieved.”

- *Bill Gates, 2005*

ENABLING A NEW CLASS OF CROSS-DEVICE, INTERACTIVE, RICH MEDIA APPLICATIONS

Examples of possible vertical collaborative applications

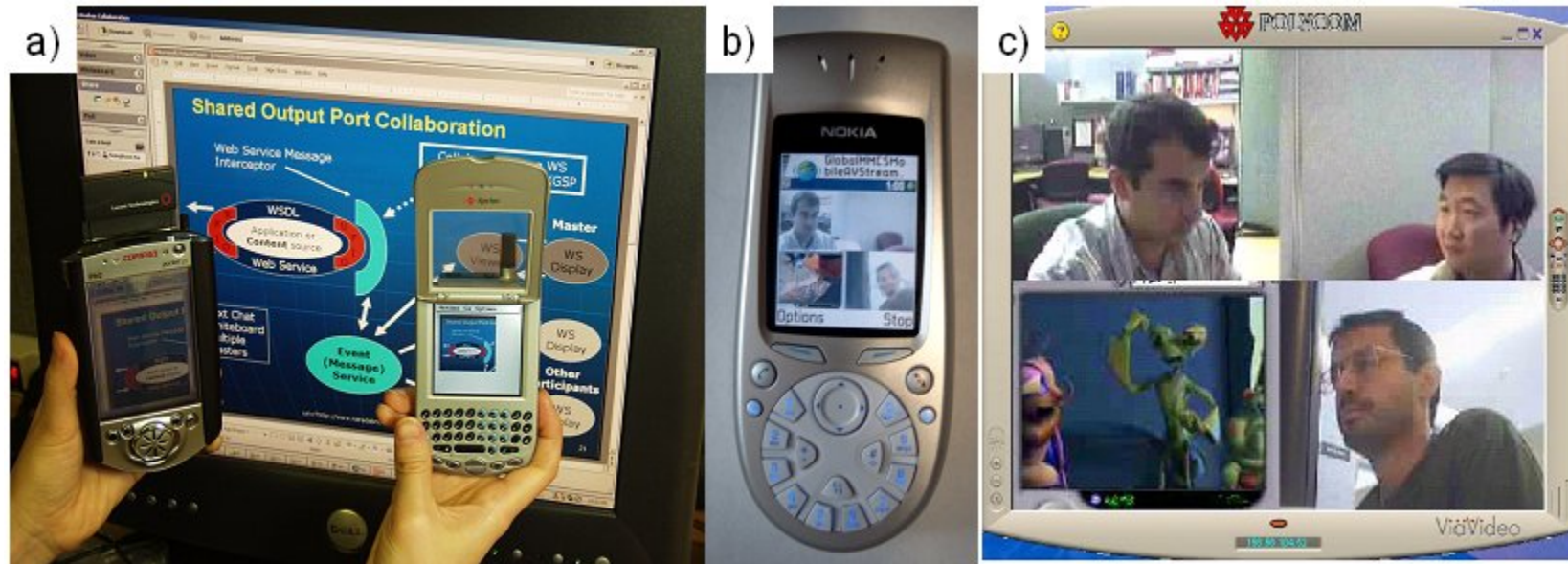


Some Earlier Work in Cross-Device Collaboration

Some screen shots of Anabas/IU CGL collaboration demos.

1. On PCs, Sprint Treo 600, Compaq iPaq, Nokia 3650 and Polycom.
2. On PCs, Sprint Treo 600, Compaq iPaq, Sprint Samsung Sph i300.
3. On PCs, Nokia N800, Lego Mindstorm NXT robots and Webcam.
4. On PCs, RFID, GPS, Ultrasonic, Sound, Light and Touch and Webcam video sensors

Cross-device collaboration – Anabas/IU



- (1) *Figure a: An Impromptu collaboration client runs on a **PC** and shares with a **Sprint Treo 600** handset and a **Compaq iPaq** PDA.*
- (2) *Figure b and c: 3 Webcam streams and an animation stream being shared between a **Nokia 3650** and **Polycom** device.*

Anabas/IU CGL Cross-Device Collaboration



An Anabas Impromptu collaboration client runs on a **PC** and shares a presentation with a **Sprint Treo 600** handset, a **Sprint Samsung Sph i300** handset and a **Compaq iPaq** PDA.

Back to the questions:

How about a cross-device mobile application?

- Do all the great things with mobile camera, GPS, maps, GIS, compass
- Capture the lovely view of the surroundings with environment data
- Add annotations and overlays
- Share it synchronously with not only social networks on mobiles but also devices like a digital picture frame in grand-parents house

What is a viable, consistent architecture to support this application and all others ?

Objectives for a Collaborative Sensor-Rich Application Development Framework

To enable easy

- development
- deployment
- management
- real-time visualization
- organization
- presentation

of collaborative sensor-rich applications.

Our definitions:

- A sensor is a time-dependent stream of information. A sensor is a resource. The sensor could be external, such as a TV stream.
- Grid computing enables any level of virtualization of resources so that users/applications do not need to know where the resources are before accessing to or interacting with them.
- A sensor grid virtualizes distributed, heterogeneous sensors allowing transparent access to, sharing of and interaction with any deployed sensors, any time, any where.

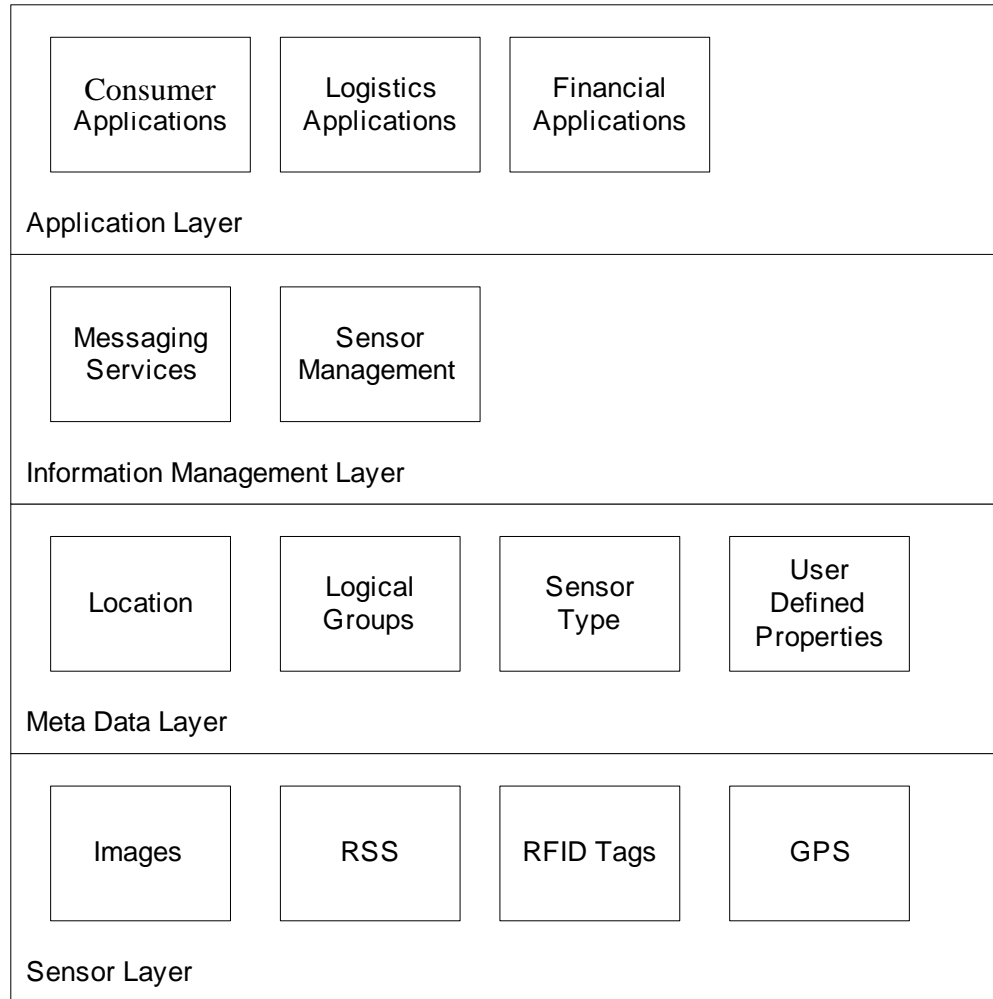
Introduction – Grid & Services

- Grids and Cyber-infrastructure have emerged as key technologies to support distributed activities that span scientific data gathering networks with commercial RFID or (GPS enabled) cell phone nets.
- Phoenix extends the Grid implementation of SaaS (Software as a Service) to SensaaS (Sensor as a service) with a scalable architecture consistent with commercial protocol standards and capabilities.
- Phoenix further extends the support of Software as a Sensor, in which case SensaaS includes Software as a Service in a unified framework.

Commercial Backdrop

- XaaS or X as a Service is dominant trend
- X = S: Software (applications) as a Service
- X = I: Infrastructure (data centers) as a Service
- X = P: Platform (distributed O/S) as a Service
- Grids are any collection of Services and manage distributed services or distributed collections of Services i.e. Grids to give Grids of Grids
- We added
- X = C: Collections (Grids) as a Service and
- X = Sensors as a Service

High-level Phoenix System Architecture



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Sensor Layer

- Sensors provide raw information which is captured dynamically in different environments.

Metadata Layer

- Describes the properties of sensor; gives meaning to raw data collected from sensors. Makes information filtering possible.

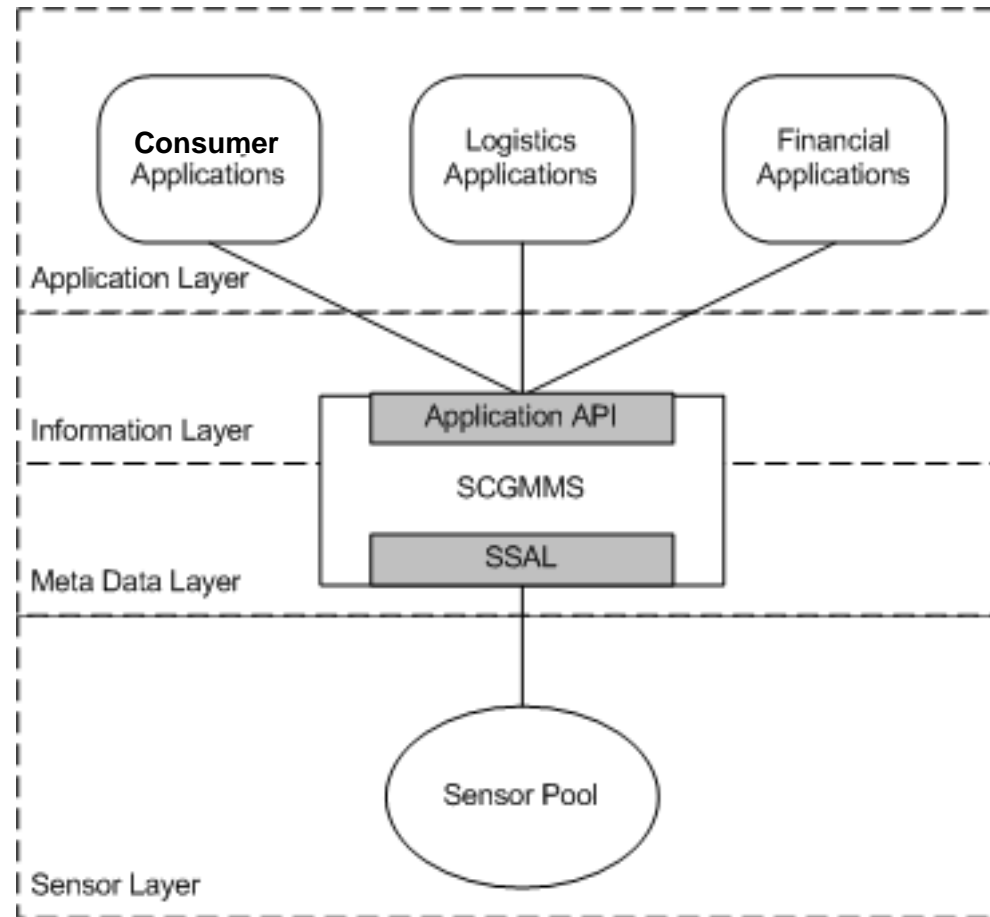
Information Management Layer

- Transport messages from sensors to applications
- Messaging facilities that supports multi-protocol
- Facilities for sensor management such as deploying and disconnecting sensors

Application Layer

- Applications access to virtualized, distributed resources

Phoenix: A Collaborative Sensor-Centric Application Development Framework



Phoenix API allows application developers to retrieve sensor data and metadata about sensors. The Phoenix SSAL facilitates sensor developers to define sensor metadata for application-level filtering and exposes sensor services to applications.

Typical Sensor Grid Interface

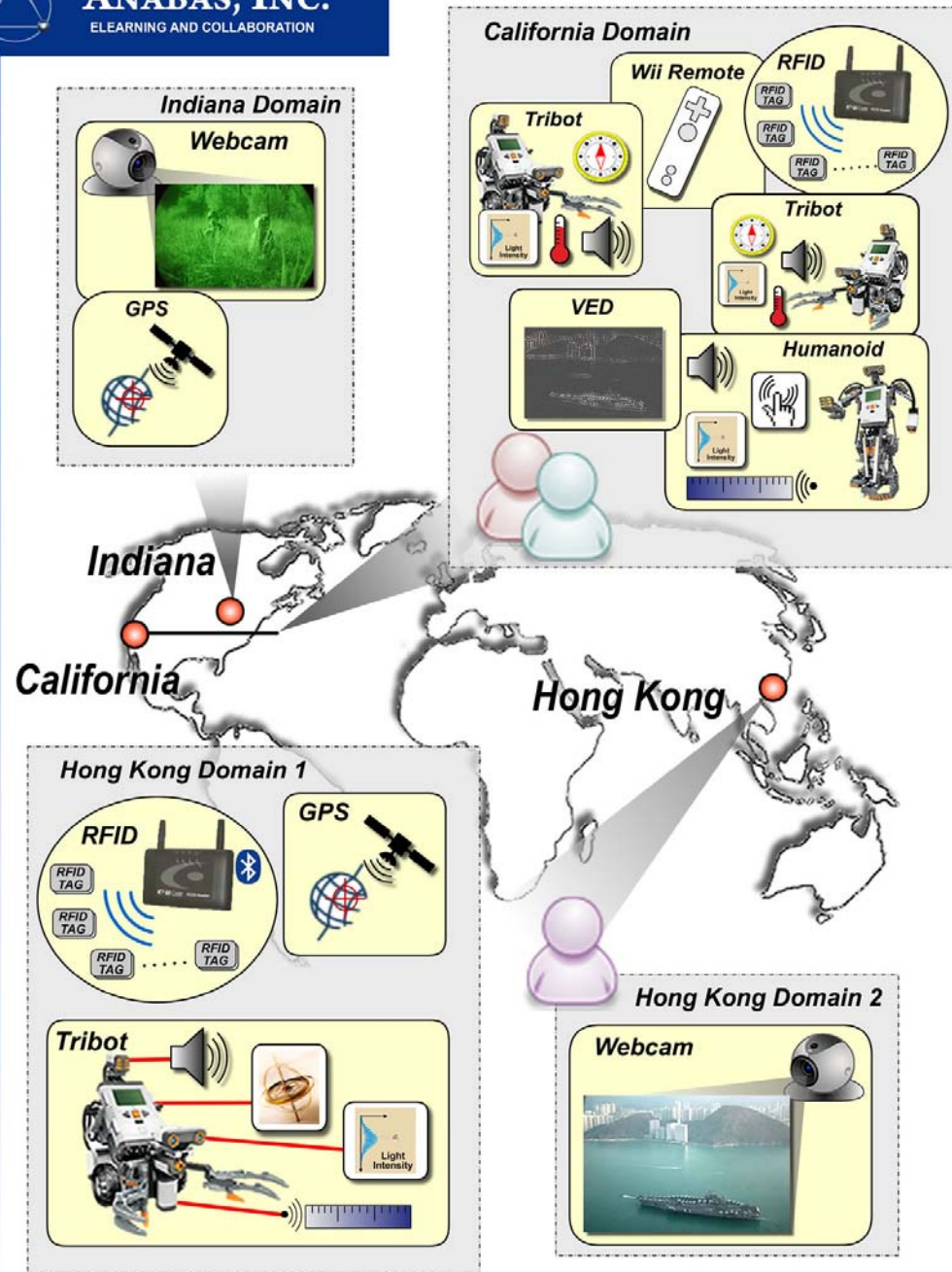
The screenshot displays the 'Impromptu - Demo' interface, which is a sensor grid management tool. The interface is divided into several key sections:

- Left Panel (Control and Participants):** Contains a menu for different UDOPs (Video, Whiteboard, Share, GeoSpatial, Robot Demo), sensor controls (Sensor Filter, Sensor ID, Group ID, Sensor Type, City), and a list of participants (Reno SC07, Bloomington, Hong Kong). A callout bubble labeled 'Different UDOPs' points to the menu, and another labeled 'Participants' points to the participant list.
- Central Presentation Area:** A large area containing four maps and their corresponding data graphs. The top-left map is labeled 'Alpha - GPS' and shows a street grid with a blue location pin. The top-right graphs show 'Sound Intensity' (Volume in dBA) and 'Distance' (cm) over time. The bottom-left graph shows 'RFID Signal Strength' (dBm) over time. The bottom-right map is labeled 'Beta - GPS' and shows a different street grid with a blue location pin. A callout bubble labeled 'Presentation Area' points to this central section.
- Right Panel (Sensor List):** A list of sensors grouped by location (Alpha and Beta). The list includes various sensor types such as GPS, Robot Sensors, Video, Vision, and RFID. A callout bubble labeled 'Sensors Available' points to this list.

The interface also features a top navigation bar with 'Previous' and 'Next' buttons, an 'Address' field, and a 'Browse' button.

A Sneak Preview of A Sample Collaborative Sensor-Centric Grid Demo Scenario

- The robots in the demo are Lego NXT Mindstorm robots.
- Each NXT robot carries some sensors – just like some new mobiles do.



Supported Services

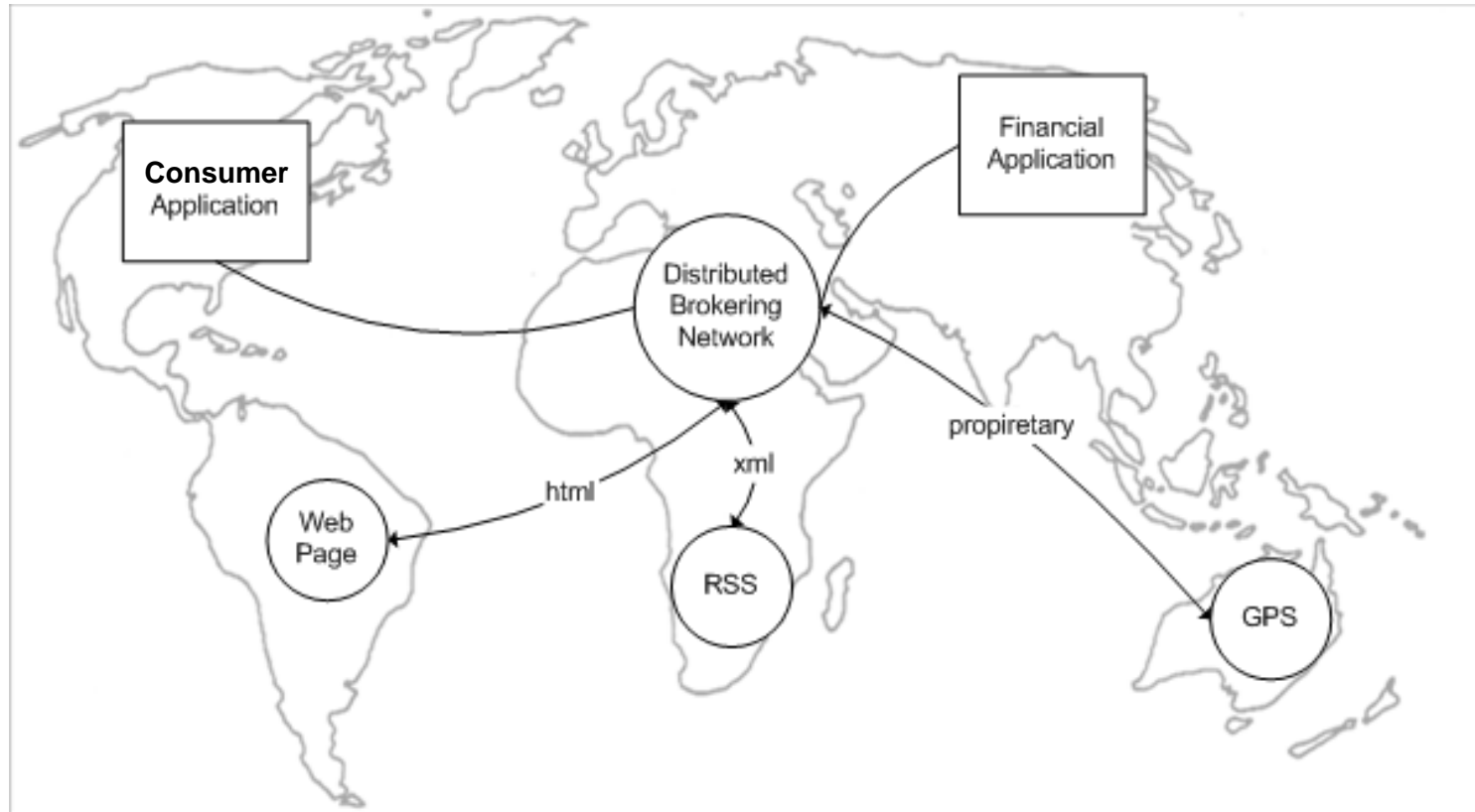
Sensor Services:

- RFID
- GPS
- Wii remote
- Webcam video
- Lego Mindstorm NXT
 - Ultrasonic
 - Sound
 - Light
 - Touch
 - Gyroscope
 - Compass
 - Accelerometer
 - Thermistor
- [NOKIA N800 Internet Tablet](#)

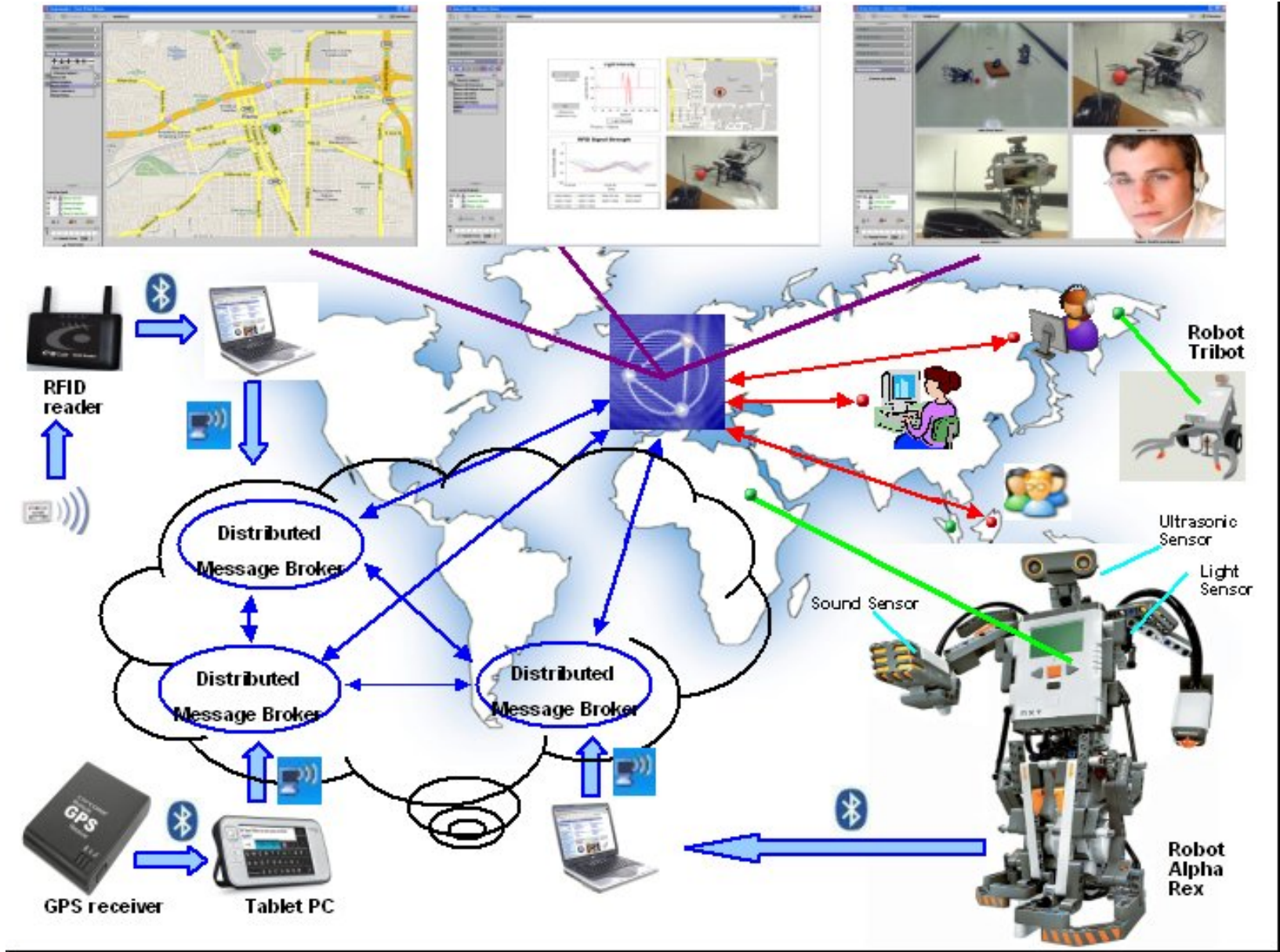
Computational Service

- VED (Video Edge Detection)

Distributed Architecture for Data Access



Illustrative Distributed Architecture for Data Access (including a Nokia N800)



Data Model

- Sensors in different geo-spatial locations continuously publish data into the distributed brokering network.
- Phoenix routes relevant data to all connected applications according to their client-side requirements.
- Applications are notified for each data arrival.
- Some sensors are capable of receiving requests from applications and perform some actions in return.
- Sensors data could be routed to other computational services for further processing.

Data Selection and Filtering

- Each Phoenix client application is only interested in certain domain-specific information extracted from the large raw data pool supported by Phoenix.
- Filtering mechanism allows
 - an application user to define “filters”
 - a filter is sent to Phoenix
 - Phoenix responds with sensors data that match the filter
 - the application subscribes to data of these sensors through the Phoenix API

An example of a filter in Phoenix

A decision-maker wants to locate all GPS and RFID sensors in US or UK, the corresponding query looks like:

**sensorType=GPS \cap sensorType=RFID \cap location=US \cup
sensorType=GPS \cap sensorType=RFID \cap location=UK**

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A sample Phoenix-capable sensor-centric application provides a GUI to support ease of filtering.

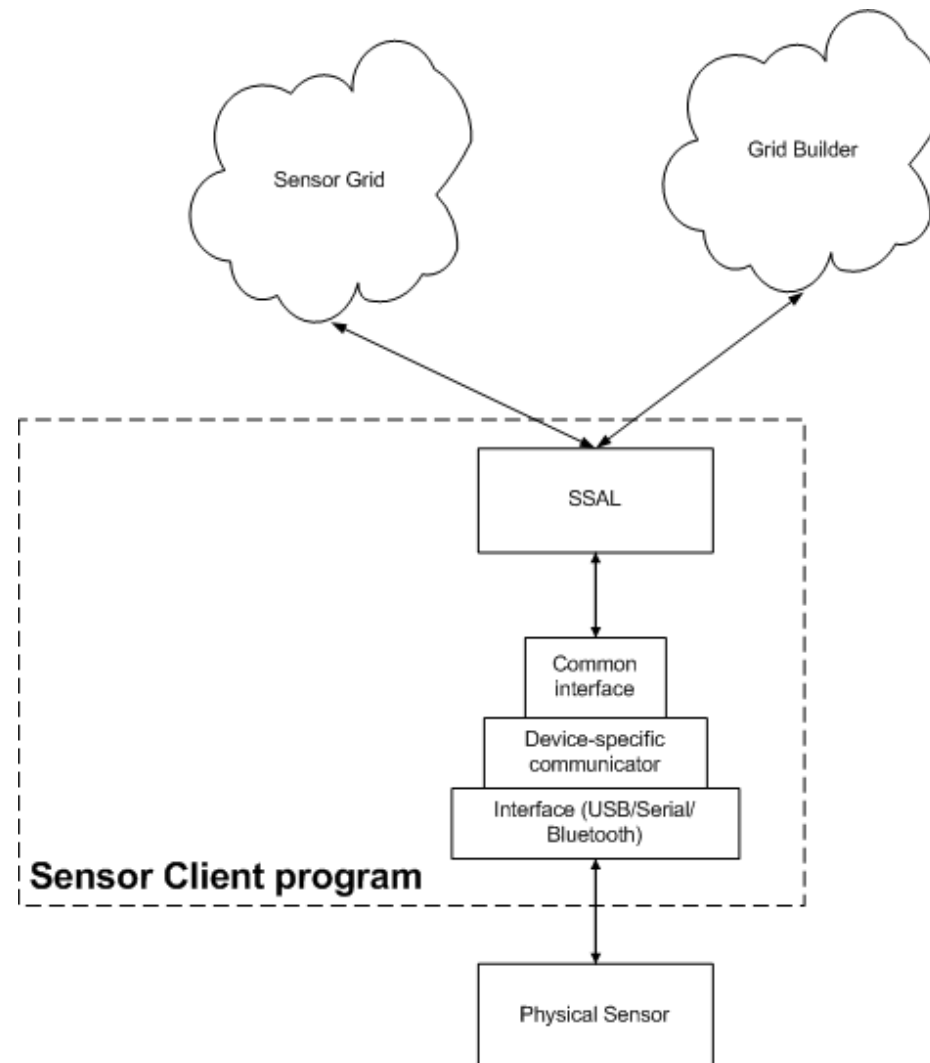
The screenshot displays a GUI window titled "Sensor Controls". At the top, there is a dropdown menu with the text "-- Please Select --". Below this is a section labeled "Sensor Filter" containing four input fields: "Sensor ID:", "Group ID:", "Sensor Type:", and "Location:". Each field has a small downward arrow on its right side. Below the input fields are two buttons labeled "OR" and "AND". Underneath these buttons is a section labeled "Filter to Apply:" which contains a list of filter rules: "sensorType=GPS", "[AND] sensorType=RFID", "[AND] location=US", "[OR] sensorType=GPS", "[AND] sensorType=RFID", and "[AND] location=Hong Kong". The list is enclosed in a scrollable box with a vertical scrollbar on the right and a horizontal scrollbar at the bottom. At the bottom of the window are two buttons: "Apply Filter" and "Reset".

Grid Builder (GB)

GB is a sensor management module which provides services for

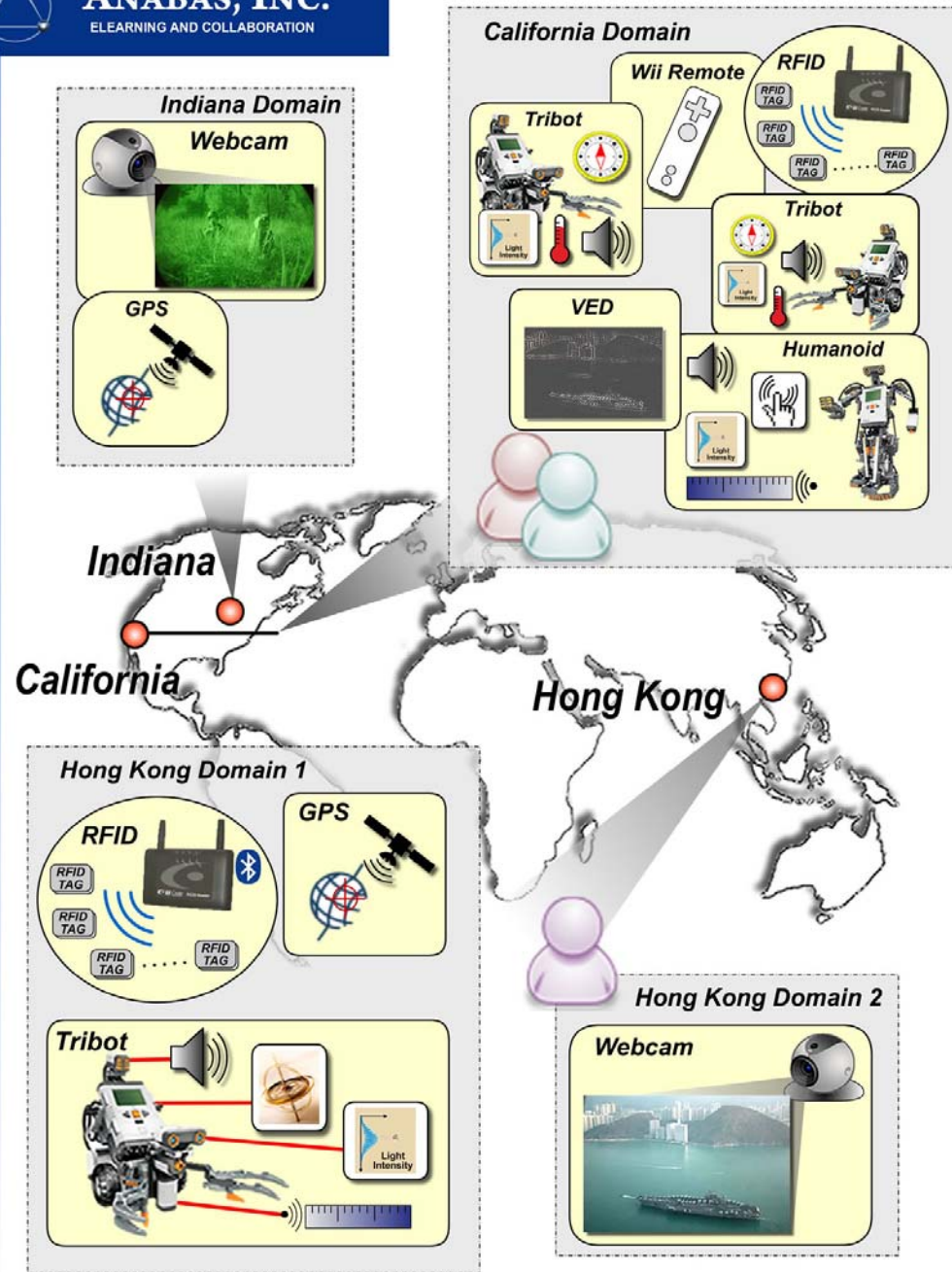
- Defining the properties of sensors
- Deploying sensors according to defined properties
- Monitoring deployment status of sensors
- Remote Management - Allow management irrespective of the location of the sensors
- Distributed Management – Allow management irrespective of the location of the manager / user

Sensor Grid (SG)



A Collaborative Sensor-Grid Demo

-- An illustrative demo in CTS 2008



Supported Services

Sensor Services:

- RFID
- GPS
- Wii remote
- Webcam video
- Lego Mindstorm NXT
 - Ultrasonic
 - Sound
 - Light
 - Touch
 - Gyroscope
 - Compass
 - Accelerometer
 - Thermistor
- [NOKIA N800 Internet Tablet](#)

Computational Service

- VED (Video Edge Detection)

Video

Whiteboard

Share

GeoSpatial

Robot Demo

Sensor Controls

VED_HK @ irvine

Sensor Filter

Sensor ID:

Group ID:

Sensor Type:

City:

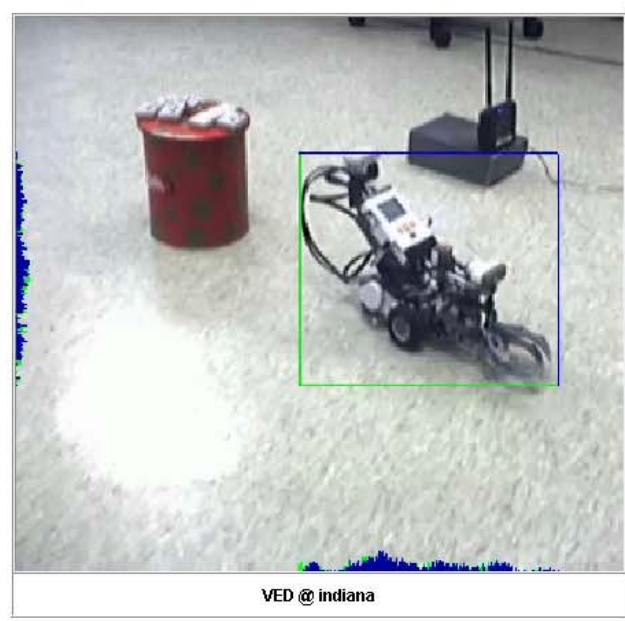
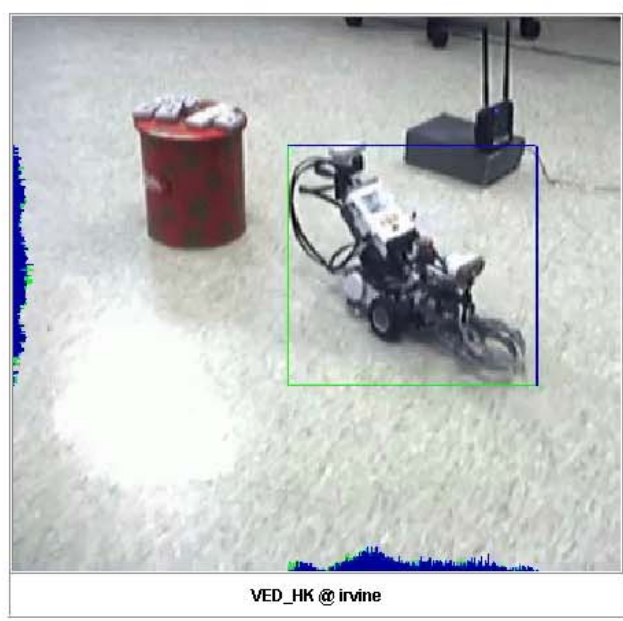
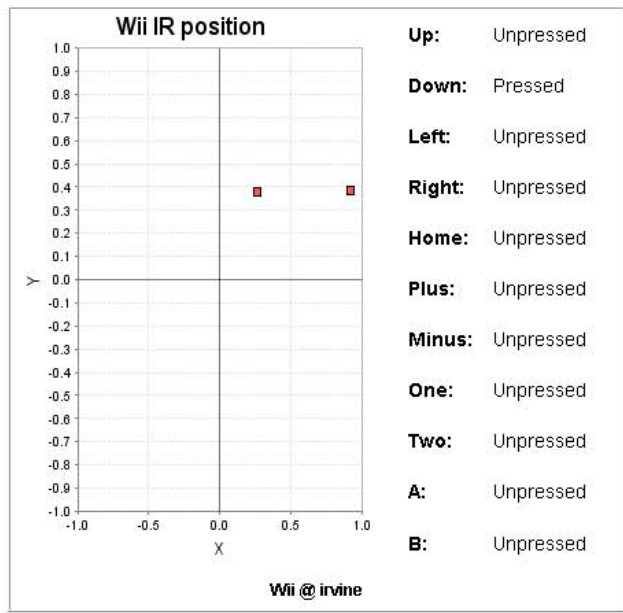
Filter to Apply:
No Filter

I am the host

John Doe
Observer

2 0 0

Hands Free



RFID

rfid @ hk: RFCMII - 000188

rfid @ hk: RFCMII - 000198

rfid @ hk: RFCMII - 000224

rfid @ irvine

rfid @ irvine: LOCATE - 00

rfid @ irvine: LOCATE - 00

rfid @ irvine: LOCATE - 00

Wii @ irvine

Video @ hk

Video @ indiana

Video @ irvine

VED @ indiana

VED_HK @ irvine

Video **Whiteboard** **Share** **GeoSpatial** **Robot Demo**

Sensor Controls
VED_Irvine @ irvine

Sensor Filter
Sensor ID:
Group ID:
Sensor Type:
City:

AND OR

Filter to Apply:
No Filter

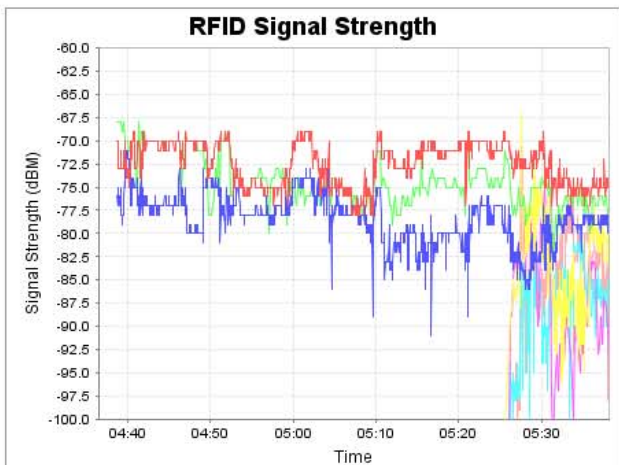
Apply Filter Reset

I am the host
John Doe
CTS Viewer
Observer

3 0 0

Hands Free Talk

Text Chat

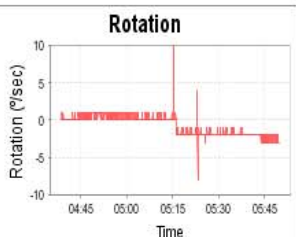
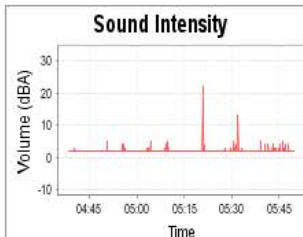


- LOCATE - 00019991
- LOCATE - 00020010
- LOCATE - 00014488
- LOCATE - 00011388
- RFCMII - 00018970
- LOCATE - 00011392
- LOCATE - 00000774

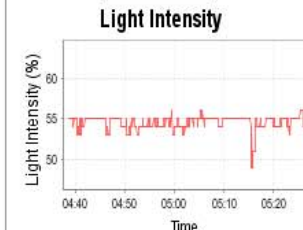
rfid @ irvine



Video @ irvine



- Sound Sensor
- Gyro Sensor



Empty Port!

Tribot @ irvine



VED_Irvine @ irvine

- rfid @ hk: LOCATE - 00011
- rfid @ hk: LOCATE - 00013
- rfid @ hk: RFCMII - 000184
- rfid @ hk: RFCMII - 000187
- rfid @ hk: RFCMII - 000188
- rfid @ hk: RFCMII - 000188
- rfid @ hk: RFCMII - 000198
- rfid @ hk: RFCMII - 000224
- rfid @ irvine
- rfid @ irvine: LOCATE - 000
- rfid @ irvine: LOCATE - 000
- rfid @ irvine: LOCATE - 000
- rfid @ irvine: LOCATE - 000

Video

Whiteboard

Share

GeoSpatial

Robot Demo

Sensor Controls

Humanoid @ irvine

-- Please Select --

Humanoid @ irvine

Tribot @ hk

Tribot @ irvine

VED_HK @ irvine

VED_Irvine @ irvine

Sensor Type:

City:

AND OR

Filter to Apply:

No Filter

Apply Filter Reset

I am the host

John Doe

Observer

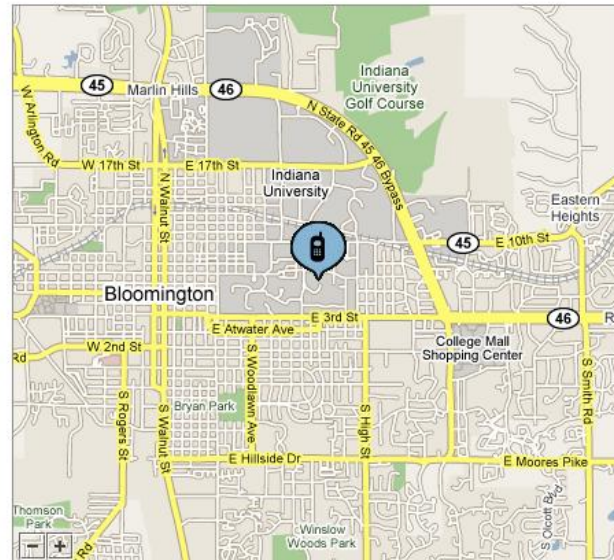
2 0 0

Hands Free Talk

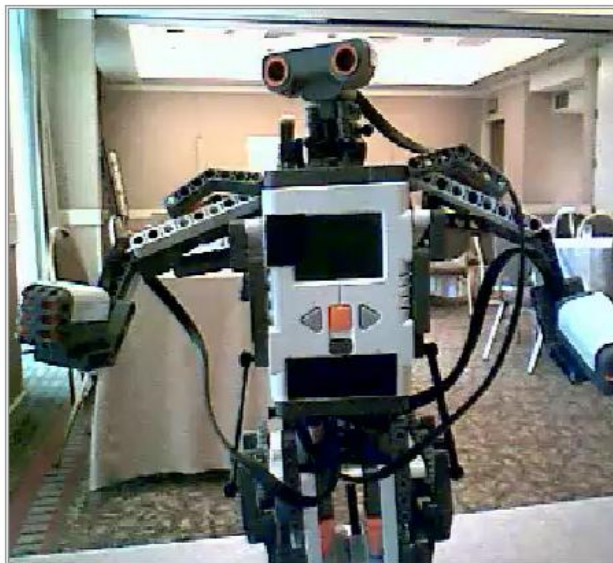
Text Chat



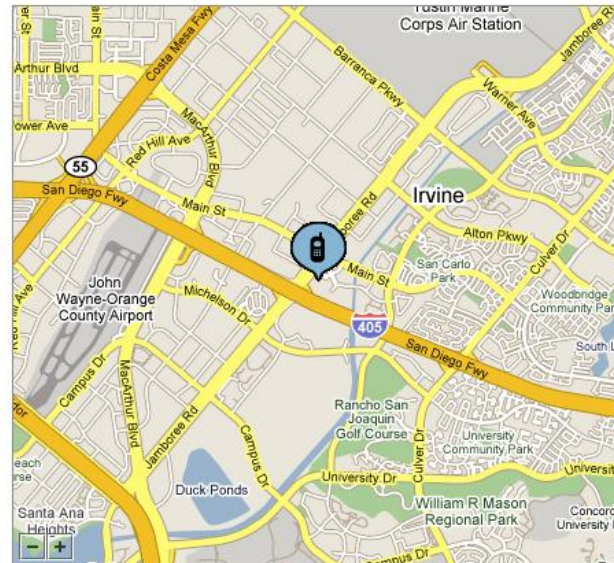
Video @ indiana



Gps @ indiana



Video @ irvine



gps @ irvine

- Gps @ indiana
- gps @ hk
- gps @ irvine
- Humanoid @ irvine
- Tribot @ hk
- Tribot @ irvine
- rfid @ hk
- rfid @ hk: LOCATE - 00011
- rfid @ hk: LOCATE - 00011
- rfid @ hk: LOCATE - 00011
- rfid @ hk: LOCATE - 00013
- rfid @ hk: RFCMII - 000184
- rfid @ hk: RFCMII - 000187

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Sensor Controls

Tribot @ hk

Sensor Filter

Sensor ID:

Group ID:

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City:

AND OR

Filter to Apply:

No Filter

Apply Filter Reset

I am the host

John Doe
Observer

2 0 0

Hands Free Talk

Text Chat



video @ irvine



GPS @ irvine



Video @ hk



gps @ hk

GPS @ irvine

gps @ hk

Humanoid @ irvine

Tribot @ hk

rfid @ hk

rfid @ hk: LOCATE - 00011

rfid @ hk: LOCATE - 00011

rfid @ hk: LOCATE - 00011

rfid @ hk: LOCATE - 00013

rfid @ hk: RFCMII - 000184

rfid @ hk: RFCMII - 000187

rfid @ hk: RFCMII - 000188

rfid @ hk: RFCMII - 000188

Video ▶

Whiteboard ▶

Share ▶

GeoSpatial ▶

Robot Demo ▼

Sensor Controls

VED_Irvine @ irvine

Sensor Filter

Sensor ID:

Group ID:

Sensor Type:

City:

AND OR

Filter to Apply:

No Filter

Apply Filter Reset

I am the host

John Doe
Observer

2 0 0

Hands Free Talk ?

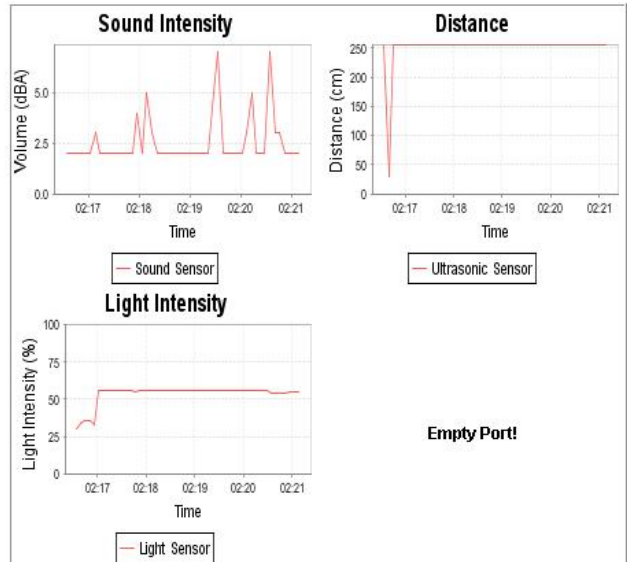
Text Chat



Video @ irvine



VED_Irvine @ irvine



Tribot @ irvine



Video @ hk

- rfid @ hk: RFCMII - 000188
- rfid @ hk: RFCMII - 000188
- rfid @ hk: RFCMII - 000198
- rfid @ hk: RFCMII - 000224
- rfid @ irvine
- rfid @ irvine: LOCATE - 00
- rfid @ irvine: LOCATE - 00
- rfid @ irvine: LOCATE - 00
- Wii @ irvine
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- Video @ irvine
- VED_HK @ irvine
- VED_Irvine @ irvine

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Sensor ID:

Group ID:

Sensor Type:

City:

AND OR

Filter to Apply:

No Filter

Apply Filter Reset

I am the host

John Doe
 Observer

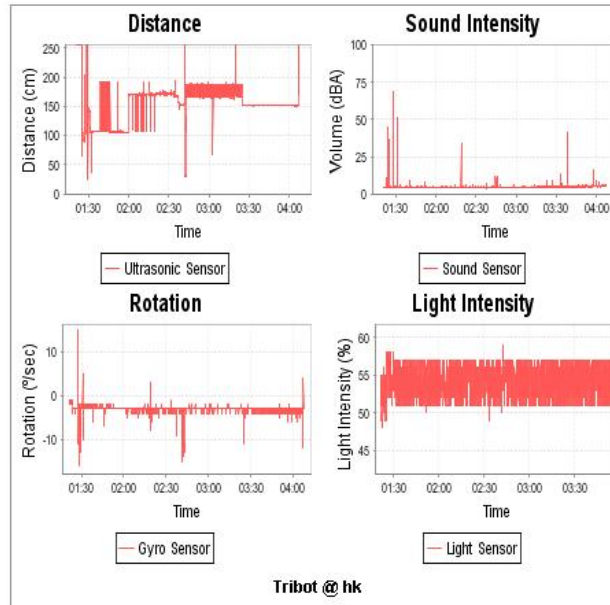
2 0 0

Hands Free Talk

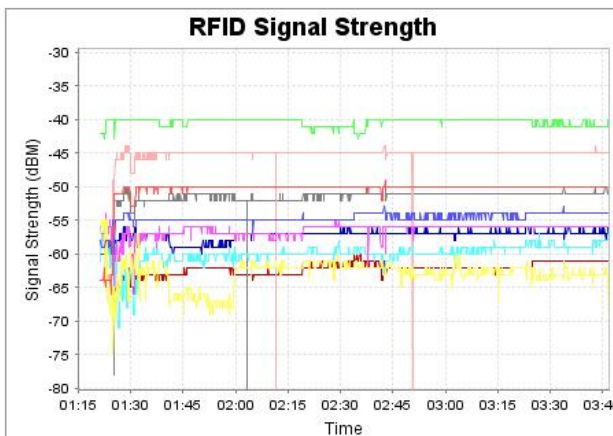
Text Chat



Video @ hk



Tribot @ hk



rfid @ hk



GPS @ irvine

gps @ hk

Humanoid @ irvine

Tribot @ hk

rfid @ hk

rfid @ hk: LOCATE - 00011

rfid @ hk: LOCATE - 00011

rfid @ hk: LOCATE - 00011

rfid @ hk: LOCATE - 00013

rfid @ hk: RFCMII - 000184

rfid @ hk: RFCMII - 000187

rfid @ hk: RFCMII - 000188

rfid @ hk: RFCMII - 000188

Recap

Test Case 1: How about an interesting yet challenging cross-device mobile application? Can it be done easily?

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Test Case 2: For the sake of stimulating thoughts and deriving architectural requirements, how would one develop an Android Jigsaw-like whiteboard application **easily** on Symbian?

Question: What is a viable, consistent architecture to support easy development and deployment of these test case applications and all others we looked at earlier?

Conclusion

- High level approach to Test Case 1: Cross-device Sharing
 - Develop mobile phone as a SensaaS (just like an NXT robot) .
 - Develop digital picture frame as a SensaaS.
 - Deployed both SensaaS on the Phoenix Sensor Grid.
- High level approach to Test Case 2: Jigsaw-like Whiteboard on Symbian
 - Use the Test Case 1 “mobile phone as a SensaaS”.
 - Add annotation and drawing features as Jigsaw.
 - Develop all image processing capabilities as SensaaS on Windows or Linux. Image processing algorithms could be developed much easier and run much faster on Windows or Linux PCs than Symbian on mobiles. These algorithms are most likely even exist in some source form. Just wrapped them as SensaaS and saving all the time to re-invent an optimized implementation on Symbian.
 - Leverage the Nokia mobile Internet.
 - Deploy all relevant SensaaS on the Phoenix Sensor Grid.
 - SensaaS streams can be shared synchronously without additional coding.

Conclusion

- Phoenix provides a unified architecture to support Collaborative Sensor-Rich applications by treating “XaaS” uniformly. It supplements *Connecting People* with *Connecting Resources*.
- Phoenix enables a new class of sensor-rich, streaming mobile application development, deployment, management and delivery platform for leading mobile service providers. It enables mobile service providers to serve all the mobile streaming needs of their end users and application developers.
- As mobile sensor streaming traffic traverses the Phoenix sensor grid, a StreamingTube™ SensaaS could be added to support storage and asynchronous access to the world of streaming content that originates from or is destined for mobiles.